

Sound radiation from a loudspeaker, from a spherical pole cap, and from a piston in an infinite baffle¹

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Abstract

Loudspeakers are often modelled as a rigid piston in an infinite baffle. As a model for real loudspeakers, this approach is limited in two ways. One issue is that a loudspeaker cone is not rigid, and a second issue is that a loudspeaker is mostly used in a cabinet. Both issues are addressed here by developing the velocity of the radiator in terms of orthogonal polynomials known from optical diffraction theory as Zernike circle polynomials. Using these polynomials we develop semi-analytic expressions for the sound pressure from the radiator in two different cases: as a flexible flat radiator mounted in an infinite baffle, and as the cap of a rigid sphere. In the latter case the comparison is done not only for the pressure but also for other quantities viz. the baffle-step response, sound power and directivity, and the acoustic centre of the radiator. These quantities are compared with those from a real loudspeaker. Finally, in the case of the baffled-piston radiation the spatial impulse response is presented.

these polynomials to the point-spread function.

In recent years, the Nijboer-Zernike approach has been applied to solve forward and inverse problems in acoustical radiation from a flexible circular piston surrounded by a rigid infinite planar set (baffle) and from a flexible spherical cap on a rigid sphere [1-11]. The flexibility is embodied by a non-uniform velocity profile v that is assumed to be radially symmetric in the case of piston radiation and axially symmetric in the case of radiation from the cap. As in optical diffraction theory, the complex amplitude of the sound pressure in the baffled-piston case is given by a Rayleigh integral comprising the field point \mathbf{r} in front of the baffle and the wave number k of the harmonic excitation applied to the piston with velocity profile v . The frequencies that are used in acoustics (20 Hz-20 kHz in audio and up to 200 kHz in ultrasound) are so much lower than those used in optics that dispersion effects can be neglected. Furthermore, although the phenomenon of focusing does manifest itself in acoustics (especially at higher frequencies), this does not usually occur to an extent that one can speak of a focal volume as in optics.

Despite all these differences with optics, a wealth of analytic results, with the basic result of the classical Nijboer-Zernike theory as cornerstone, have been obtained for piston radiation and also for radiation from a spherical cap. In both cases, the non-uniform velocity profile is considered to be developed as a series involving the Zernike polynomials (appropriately modified in the case of spherical-cap radiation). The contribution of each of these Zernike terms to the pressure and various other acoustical quantities turns

1. Nijboer-Zernike approach in acoustics: ANZ

The Nijboer-Zernike (NZ) approach in Optics is a method to compute optical point-spread functions for circular, focused, optical systems in the presence of aberrations. The approach has been devised by Zernike (1934) and his student Nijboer (1942), and the key features of it are expansion of non-uniformities in the exit pupil as a series of Zernike circle polynomials together with a convenient analytic result for the contribution of each of

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out to have a tractable form, and so the corresponding quantity for the velocity profile can be obtained in semi-analytic form by linear superposition. Due to the efficiency of the Zernike terms in representing velocity profiles through their expansion coefficients, this offers the opportunity to estimate an unknown velocity profile v on the level of expansion coefficients from measured data in the field.

Here one can use a matching approach in which the unknown expansion coefficients are found by requiring an optimal match between the measured data and the theoretical expression comprising the coefficients.

2. Far-field pressure obtained from near-field measurements

In Fig. 1 below we have plotted the analytic expression for the far-field pressure in case of baffled-piston radiation due to the first four radially symmetric Zernike terms. The wave number k of the applied harmonic excitation and the angle θ between the acoustical axis (perpendicular to the baffle and passing through the centre of the circular piston) and the line segment connecting piston centre and field point r , have been combined into the single variable $ka \sin \theta$ (a being the piston radius).

In the case that we have a non-uniform velocity profile that can be accurately represented as a linear combination of these first four radially symmetric Zernike terms, one can thus compute the corresponding far-field response by linear superposition.

However, the required coefficients of such a linear combination are generally not available. It turns out that these coefficients can be estimated from measured on-axis pressure data. The key result here is an analytic expression, per radially symmetric Zernike term, for the on-axis pressure [1,3,4]. In Fig. 2 the modulus of the normalized on-axis pressure as a function of the normalized on-axis distance is plotted for the case of the first four radially symmetric Zernike terms.

The procedure then consists of estimating the unknown expansion coefficients of the piston velocity profile by matching the measured on-axis pressure data with the theoretical expression for the on-axis pressure comprising the unknown expansion coefficients. This procedure has been applied to a real loudspeaker. Thus, the on-axis pressure was measured at 10 near-field points. From these near-field data, the first four coefficients of the radially symmetric Zernike terms describing the velocity profile on the flexible membrane of the loudspeaker were estimated by matching. These four coefficients were fed into the theoretical linear superposition expression for the on-axis pressure [2,3], and the result is displayed in Fig. 3. In this figure the 10 measured on-axis pressure values at normalized axial distance are shown as the solid line connecting the data points, and the estimated on-axis pressure arising from the four estimated coefficients by linear superposition is shown as the dotted line.

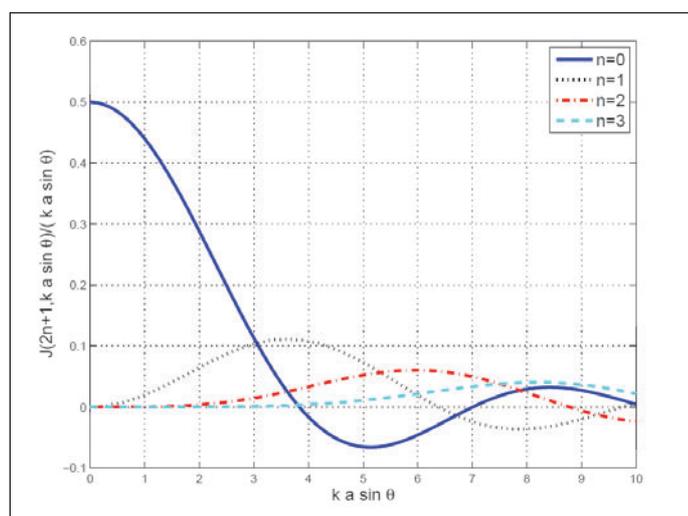


Figure 1. The far field pressure $J_{2n+1}(ka \sin \theta) / ka \sin \theta$ as a function of wave number k , piston radius a and fieldpoint angle θ , combined into the single variable $ka \sin \theta$, for the first four Zernike terms (radially symmetric).

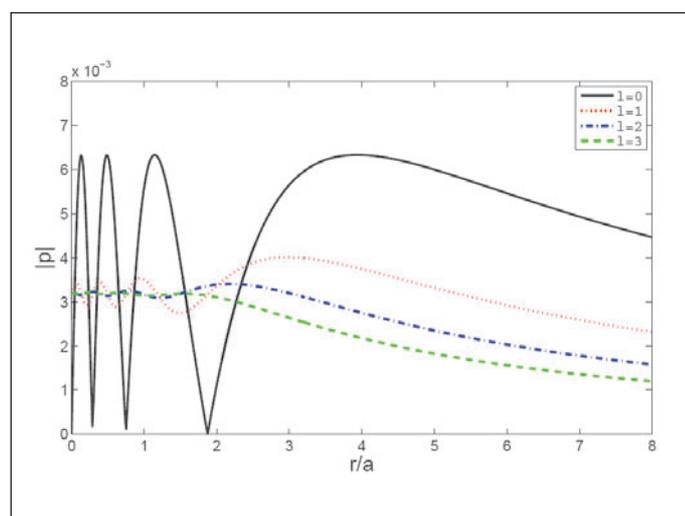


Figure 2. The modulus of the normalized on-axis pressure as a function of the normalized distance r/a for the first four radially symmetric Zernike terms.

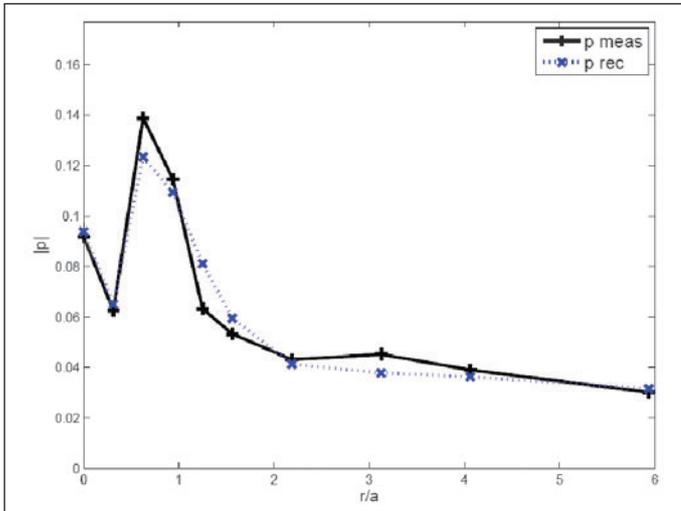


Figure 3. Measured on-axis near-field pressure data points connected by the black solid line p_{meas} and the estimated on-axis pressure p_{rec} blue dotted line, as a function of the normalized distance r/a . The loudspeaker is a Vifa MG10 SD09-08 with membrane radius $a=3.2$ cm and measured in an IEC-baffle at 13.72 kHz.

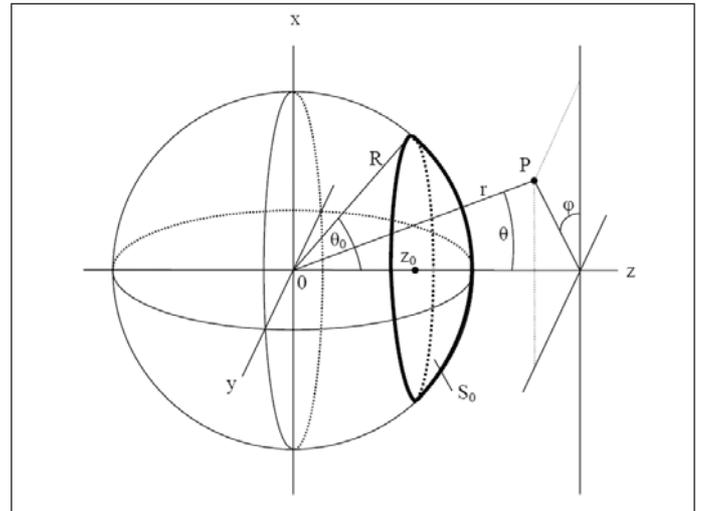


Figure 4. Geometry and notations of the pole cap S_0 .

The far-field of the loudspeaker can now also be predicted by linear superposition, using the four estimated coefficients, of the four far-field responses displayed in Fig. 1. Since the measurements were done in the near-field of the loudspeaker, an expensive measurement in the far-field of the loudspeaker by using an anechoic room has thus been avoided.

3. Comparing radiation from a loudspeaker and from a flexible spherical cap on a rigid sphere

It has been suggested by the theoretical physicists Morse and Ingard that the sound radiation of a loudspeaker in a box is comparable with that of a spherical cap on a rigid sphere, see Fig. 4 below, when the volumes of the box and sphere and the areas of the vibrating membrane and cap are matched. This has been established recently by Aarts and Janssen [7,9,11] who developed, starting from the series solution of the Helmholtz equation with spherical boundary conditions, a Zernike-based computation scheme for the sound pressure on and around the sphere.

Thus, the normal component of the velocity profile on the cap is expanded in Zernike terms (appropriately modified so as to take account of the spherical, rather than flat, nature of the moving cap), and the contribution to the pressure of any field point of each of the Zernike terms is determined in semi-analytic form. The loudspeaker (Vifa MG10SD09-08, $a= 32$ mm) was mounted in

the square side of a rectangular cabinet with dimensions of 130 by 130 by 186 mm and measured on a turntable in an anechoic room at 1 m distance, and measured by means of a PolyTec PSV-300-H scanning vibrometer with an OFV-056 laser head. A vibration pattern of this driver at 2.4 kHz, overlaid with a picture of the driver in the cabinet, is shown in Fig. 5 below.

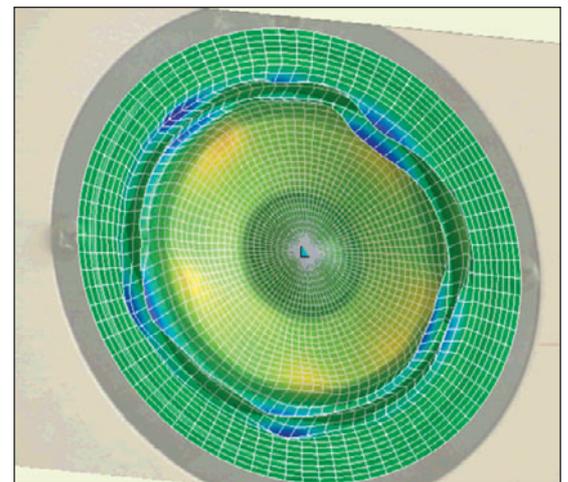


Figure 5. A vibration pattern of a driver at 2.4 kHz, overlaid with a picture of the driver in the cabinet.

In Fig. 6 three polar plots of the modulus of the pressure at four different frequencies and at one meter distance have been compared. The top figure shows the polar plot of a real loudspeaker (the same loudspeaker as the one used in Figs. 3,5). The middle figure (Fig. 6b) shows the polar plot that arises in the case of baffled-piston radiation with a rigid piston (v

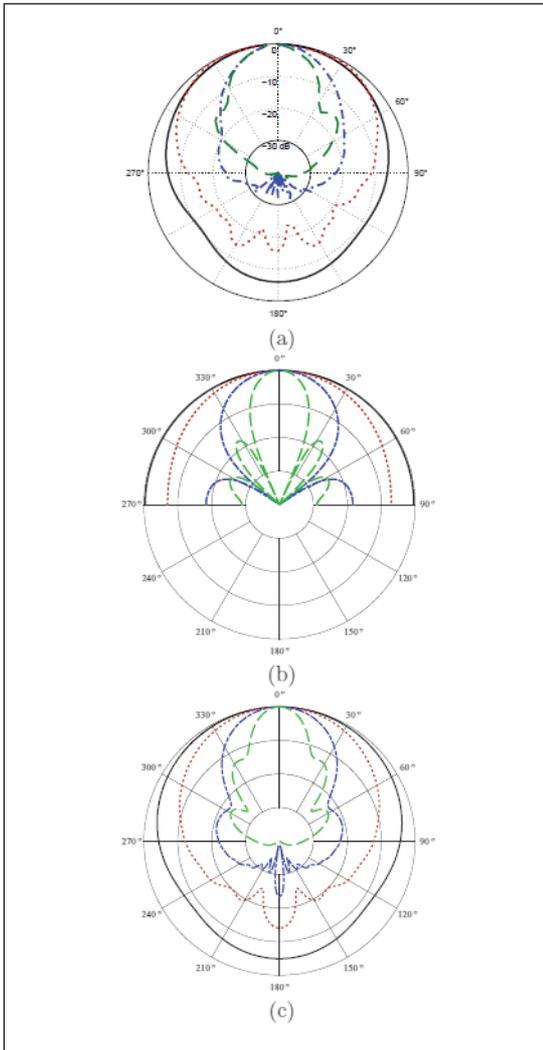


Figure 6. Polar plots of the pressure at frequency 1 kHz (solid, black curves), 4 kHz (dotted, red curves), 8 kHz (dashed-dotted, blue curves), and 16 kHz (dashed, green curves), normalized such that the pressure is 1 at $\theta=0$ for a) loudspeaker (same as in Fig. 5) in a rectangular cabinet measured at 1 m distance, b) rigid piston in an infinite baffle, piston radius $a=3.2$ cm, using far-field response of Fig. 1, $n=0$, c) rigid spherical cap with z-component of the velocity profile equal to 1 m/s, cap aperture $\theta_0=\pi/8$, and $r=1$ in the Aarts-Janssen scheme [9].

is constant on the piston), and for this the analytic result shown in Fig. 1, $n=0$, has been used. The lower figure (Fig. 6c) shows the polar plot of a flexible spherical cap in a rigid sphere with a velocity profile on the cap such that the component in the z-direction is constant, and for this the Aarts-Janssen computation scheme has been used. The area

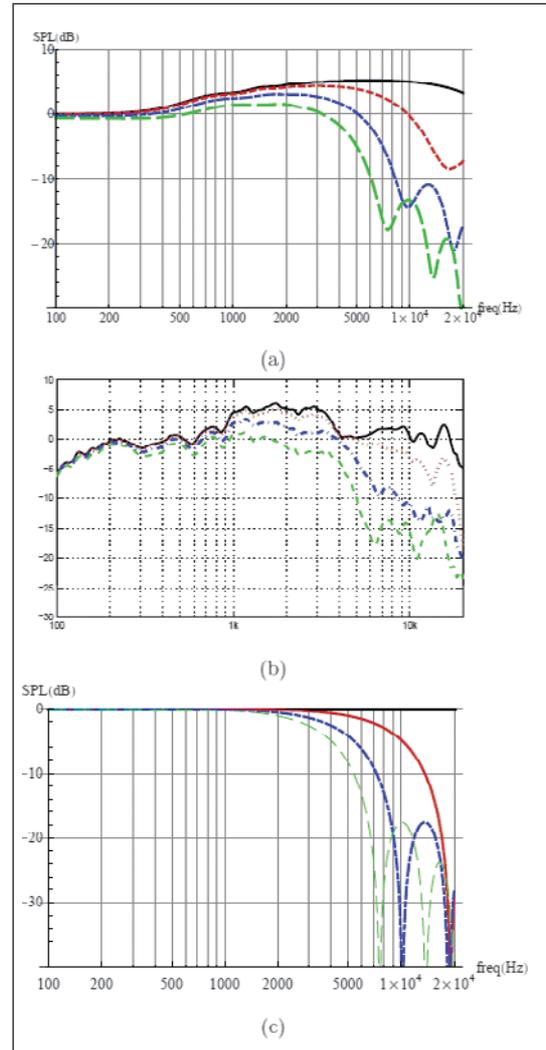


Figure 7. Frequency responses for $\theta=0$ (solid curve), $\theta=\pi/9$ (dotted curve), $\theta=2\pi/9$ (dashed-dotted curve), and $\theta=3\pi/9$ (dashed curve). (a) Baffle step of a polar cap $\theta_0=\pi/8$ on a sphere of radius $R=0.082$ m, at distance $r=1$ m, (constant velocity $V=v_0=1$ m/s). All curves are normalized such that the SPL is 0 dB at 100 Hz. (b) Frequency response of a driver (same as in Fig. 5), radius $a=3.2$ cm mounted in a square side of a rectangular cabinet with dimensions $13 \times 13 \times 18.6$ cm. The loudspeaker was measured in an anechoic room at 1 m distance. The on-axis response was normalized to 0 dB at 200 Hz, the other curves were normalized by the same amount. (c) Response of a rigid piston ($a=3.2$ cm) in an infinite baffle in the far field. All curves are normalized such that the SPL is 0 dB at 100 Hz.

of the piston and the area of the cap and the volume of the sphere have been chosen so as to be the same as the corresponding quantities of the real loudspeaker. As is apparent, the polar plots of the real loudspeaker and those obtained from the spherical-cap model resemble one another much more than the polar plots from the real loudspeaker and

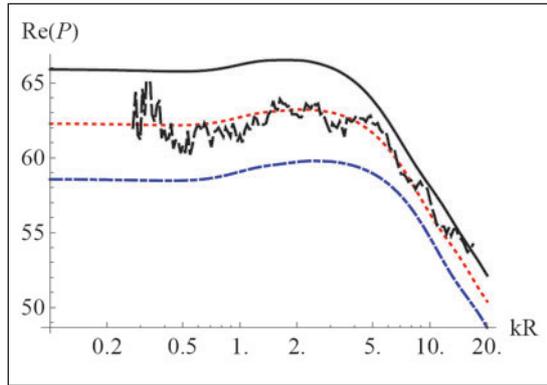


Figure 8. The power $\text{Re}[P]c/(2\pi\rho_0 a^2 R^4)$ [dB] vs. kR (log. axis) of a rigid spherical cap moving with a constant acceleration ($V=ikcV$) and various apertures, $\theta_0=5\pi/32$ (solid curve), $\theta_0=\pi/8$ (dotted curve), $\theta_0=\pi/10$ (dashed-dotted curve), sphere radius $R=8.2$ cm, together with the power from the measured loudspeaker (same as in Fig. 5) (dashed-irregular curve). The logarithmic horizontal axis runs from $kR=0.1$ -20, corresponding to a frequency range from 66 Hz-13.2 kHz.

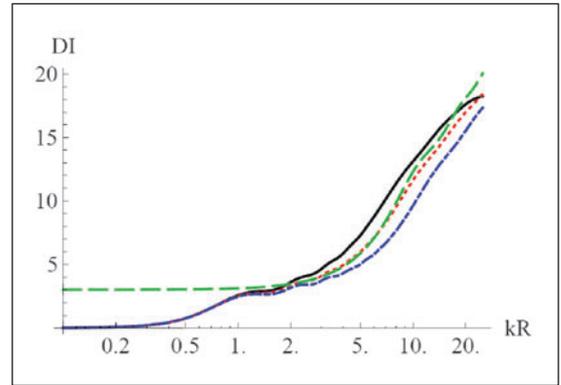


Figure 9. The directivity index DI (explained in the text) of a rigid spherical cap with various aperture angles of the cap: $5\pi/32$ rigid (solid, black curve), $\pi/8$ (dotted, red curve), and $\pi/10$ (dashed-dotted, blue curve). The long-dashed, green curve starting for $kR=0$ at 3 (dB) is the directivity for a rigid piston in an infinite baffle, using the far-field response in Fig. 1, $n=0$.

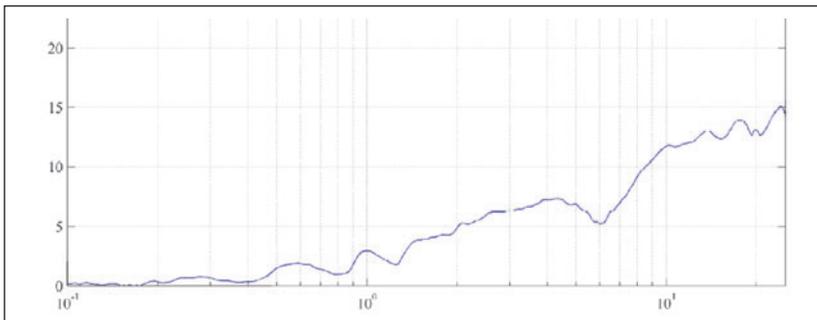


Figure 10. The directivity index DI vs. kR of the loudspeaker (same as in Fig. 5) in a rectangular cabinet measured at 1 m distance.

those obtained from the baffled-piston model. This remarkable agreement between results for the sphere model and the true loudspeaker continues to hold for several other acoustical quantities such as the baffle-step response, the power and directivity, and the acoustical centre [7,11]. In Fig. 7 we demonstrate this for the baffle-step response. At low frequencies the baffle of a loudspeaker is small compared to its wavelength and, due to diffraction effects, radiates into the full space (4π -field). At those low frequencies the radiator does not benefit from the baffle in terms of gain. At high frequencies the loudspeaker does benefit from the baffle which yields a gain of 6 dB. This transition is called the baffle step. It is seen from Figs. 7a,b that the pole-cap model produces a credible baffle-step response. In the case of radiation from a rigid piston in an infinite baffle, the baffle step is absent since all frequencies benefit equally from the (infinite) baffle.

Figure 8 shows plots of the calculated power for a rigid spherical cap moving with a constant acceleration and various apertures, $\theta_0=5\pi/32$ (solid curve), $\theta_0=\pi/8$ (dotted curve), and $\theta_0=\pi/10$ (dashed-dotted curve), together with the power obtained from the measured loudspeaker (dashed-irregular curve) [7,11].

In Fig. 9 the directivity index DI from the spherical cap model is shown, while in Fig. 10 the DI of the measured loudspeaker is given. This directivity index is a qualitative measure of how directive a particular sound radiator is: it is the $10 \log_{10}$ of the ratio of the modulus squared pressure on the axis in the far field produced by the considered radiator and the same quantity produced by a completely non-directive, point-source radiator, provided that the total radiated power of both radiators is the same [7,11]. It appears that the DI of the model and the measurement, Figs. 9 and 10 respectively, are rather similar.

The acoustic centre of a reciprocal transducer can be defined as the point from which spherical waves seem to be diverging when the transducer is acting as a source. There are, however, additional definitions. This concept is used mainly for microphones. Recently, the acoustic centre was discussed [11] for normal sealed-box loudspeakers as a particular point that acts as the origin of the low-frequency radiation of the loudspeaker. At low frequencies, the radiation from such a loudspeaker becomes simpler as the wavelength of the sound becomes larger relative to the enclosure dimensions, and the system behaves

externally as a simple source (point source). The difference between the origin and the true acoustic centre is denoted by Δ . If $p(r, 0)$ and $p(r, \pi)$ are the sound pressure at the front and at the back of the loudspeaker, respectively, then Δ follows, assuming that $R/r \gg 1$, from the ratio of these sound pressures as $\Delta = r(|q| - 1)/(|q| + 1)$, where $q = p(r, 0)/p(r, \pi)$. The pole-cap model is used to calculate the function q and is shown in Fig. 11.

It appears [11] that for modest apertures ($\theta_0 \leq 0.5$) and at low frequencies ($kR \leq 0.4$), the acoustic centre for a loudspeaker lies about $0-0.5R$ in front of the loudspeaker. Here R is a characteristic size parameter of the cabinet such as $(3V/4\pi)^{1/3}$ with V the volume of the cabinet (this equals the cabinet radius in case of a spherical cabinet). At higher frequencies, the acoustic centre shifts further away from the loudspeaker. For example, between $kR=1$ (660 Hz) and $kR=2$ (1.32 kHz) q is about 5 dB (see Fig. 11), corresponding to $\Delta = 3.4R = 280$ mm.

4. Acoustical spatial impulse response

In the case of baffled-piston radiation, the complex amplitude $p(\mathbf{r}; k)$ of the pressure at a field point \mathbf{r} in front of the baffle due to a harmonic excitation of frequency $\omega = kc$, with c the speed of sound, is given by one of the Rayleigh integrals [6,10]. Since the media are not dispersive at the relevant frequencies, this Rayleigh integral representation holds in the same form for all involved wave numbers k . In accordance with well-established practices in physical signal analysis, the spatial impulse response $\Phi(\mathbf{r}; t)$ can be obtained by performing the Fourier transform of the velocity potential associated with $p(\mathbf{r}; k)$ with respect to k in which t is the Fourier variable. This $\Phi(\mathbf{r}; t)$ is the impulse response at time $t > 0$ and at the field point \mathbf{r} due to an instantaneous volume displacement at $t=0$ of the piston with non-uniform velocity profile v vanishing outside the piston. According to the impulse response principle of acoustics, this $\Phi(\mathbf{r}; t)$ can be obtained as the integral of the velocity profile v along the arc consisting of all points on the piston that have equal distance ct to the field point \mathbf{r} . As a consequence, $\Phi(\mathbf{r}; t)$ vanishes when ct is so small or so large that the arc is non-existing or does not contain piston points. In the case that $v = v(\sigma)$, $0 \leq \sigma \leq a$, is a radially symmetric profile on the circular piston of radius a and $\mathbf{r} = (0, 0, z)$ is an on-axis point, the value of the impulse response $\Phi(\mathbf{r} = (0, 0, z); t)$ is a multiple of v

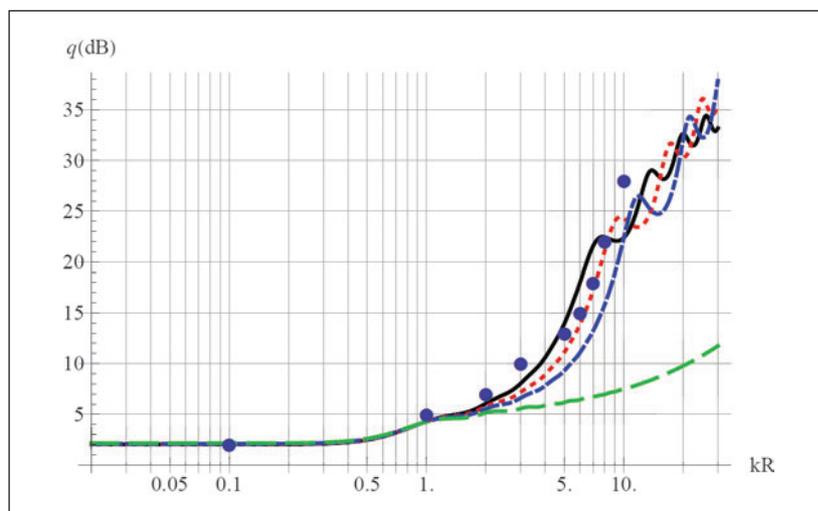


Figure 11. Function $20 \log_{10} |q|$ [dB] vs. kR (log axis) of rigid spherical cap for various apertures. — $\theta_0 = 5\pi/32$; ···· $\theta_0 = \pi/8$; - · - · $\theta_0 = \pi/10$; — simple source on sphere. Constant cone velocity V , all at $r=1$ m; sphere radius $R=82$ mm. Solid circles—real driver [same as in Fig. 5; $a=32$ mm] mounted in square side of a rectangular cabinet. Logarithmic horizontal axis runs from $kR = 0.02$ to 30, corresponding to a frequency range from 13 Hz to 19.8 kHz.

($\sigma = (c^2 t^2 - z^2)^{1/2}$) when $0 < c^2 t^2 - z^2 < a^2$ and 0 otherwise. Hence the radially symmetric profile $v(\sigma)$, $0 \leq \sigma \leq a$, is reproduced at each axial point $(0, 0, z)$ in warped form where the warping takes places according to $\sigma = (c^2 t^2 - z^2)^{1/2}$. This yields an approach to estimating velocity profiles from on-axis impulse response data.

In the case that \mathbf{r} is a general non-axial point, the resulting integral expression for the impulse response $\Phi(\mathbf{r}; t)$ is more complicated, even when v is radially symmetric. Now it turns out that the approach of developing v into a Zernike series provides the solution to the forward computation problem. Indeed, Aarts and Janssen [6,10] have shown that each of the Zernike terms involved in the expansion of v has an explicit, finite-terms expansion for the contribution to the impulse response. In Fig. 12, two impulse responses $\Phi(\mathbf{r} = (w, 0, z); t)$ are shown for the case that the normalized axial distance z/a from the piston plane equals $1/2$, as a function of the normalized radial distance w/a from the axis and the normalized time variable ct/a . Figure 12 (a) shows this impulse response for the case that v is constant on the piston (rigid piston) and Fig. 12 (b) shows the impulse response for the case that $v(\sigma) = \exp(-4(\sigma/a)^2)$, $0 \leq \sigma \leq a$. The latter velocity profile can be accurately represented using nine radially symmetric Zernike terms, and each of these Zernike terms has a finite-series expression for its contribution to the impulse response.

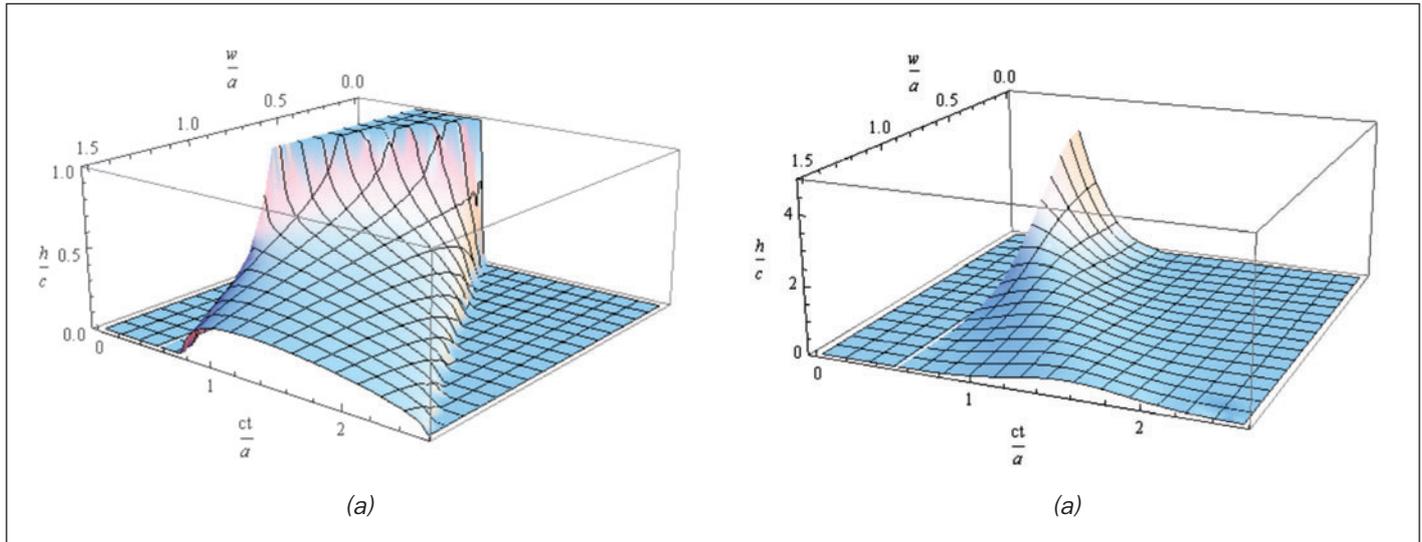


Figure 12: Spatial impulse response $\phi(w, 0, z; t)$ with constant value $z/a=1/2$ of the axial variable as a function of the normalized radial variable w/a and the normalized time variable ct/a for the cases that (a) $v(\sigma)=1, 0 \leq \sigma \leq a$, (b) $v(\sigma)=\exp(-4(\sigma/a)^2)$.

The forward computation method given above can also be used in the reverse direction in which unknown velocity profiles are estimated on the level of their expansion coefficients by matching impulse response data that is measured with the theoretical expression comprising the unknown expansion coefficients.

5. Conclusions

The Zernike circle polynomials from optics provide an efficient and robust means to describe velocity profiles of a non-rigid piston in a baffle and a flexible spherical cap on a rigid sphere. Only a few coefficients are necessary to approximate various velocity profiles. The polar plot of a rigid spherical cap on a rigid sphere has been shown to be quite similar to that of a real loudspeaker, and is useful in the full 4π -field. The cap model can be used to predict, besides polar plots, various other acoustical quantities of a loudspeaker including the sound pressure, baffle-step response, sound power, directivity, and the acoustic centre. The method enables one to solve the inverse problem of calculating the actual velocity profile of the cap radiator using (measured) on- and off-axis sound pressure data. This computed velocity profile allows the extrapolation to far-field loudspeaker pressure data, including off-axis behaviour. Using Zernike expansions of radially symmetric velocity profiles on a baffled, circular piston, a computation scheme for spatial impulse responses is feasible.

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The papers listed below are accessible through the following two websites.

<http://www.extra.research.philips.com/hera/people/aarts/>
<http://www.univie.ac.at/nuhag-php/janssen/>

A description and papers on the Extended Nijboer-Zernike (ENZ) theory is given at this website: <http://www.nijboerzernike.nl/>

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Park's noise plan upsets everyone equally

After 25 years of bureaucratic and political fights, the National Park Service soon will adopt a plan restricting noise from tourist aircraft at the Grand Canyon. But the plan is making few happy. Even the park superintendent says the plan doesn't go far enough to protect Grand Canyon's "soundscapes." Air tour operators say it will hurt their business. The plan would limit the number of flights, hours and routes that tour operators could fly over the 277-mile-long park. It also requires quieter planes and helicopters, a conversion air tour operators such as Papillon Grand Canyon Helicopters say they've already begun. "It is the best plan the park service could get given the conditions we have to deal with," says Grand Canyon Park Superintendent David Uberuaga, referring to opposition from tour operators and what he called the Federal Aviation Administration's attempts to "delay" and "sidetrack" the plan. But it is not, he says, enough to restore "natural quiet" to one of the world's natural wonders. The FAA could still recommend changes based on safety concerns after the NPS releases its plan. FAA spokesman Hank Price says the two agencies "have worked cooperatively for years to implement actions to improve aviation safety and environmental quality" at the Grand Canyon. The restrictions are one of the most significant actions in a quarter-century struggle to balance commercial tourism with the natural sounds and solitude of the outdoors. The Grand Canyon has up to 57,000 air tour flights in a year, the most of any national park. Noise-control plans are underway for other parks, but their preparation also has dragged on since the 2000 law requiring them, largely because of conflicting missions between the NPS, tasked with protecting "natural quiet," and the FAA, responsible for air safety. The Grand Canyon plan would cap the number of annual air tour flights at 65,000, 14% more than the previous high. But hours around sunset and sunrise would be off-limits, and planes and helicopters would be required to have noise-abating technology.